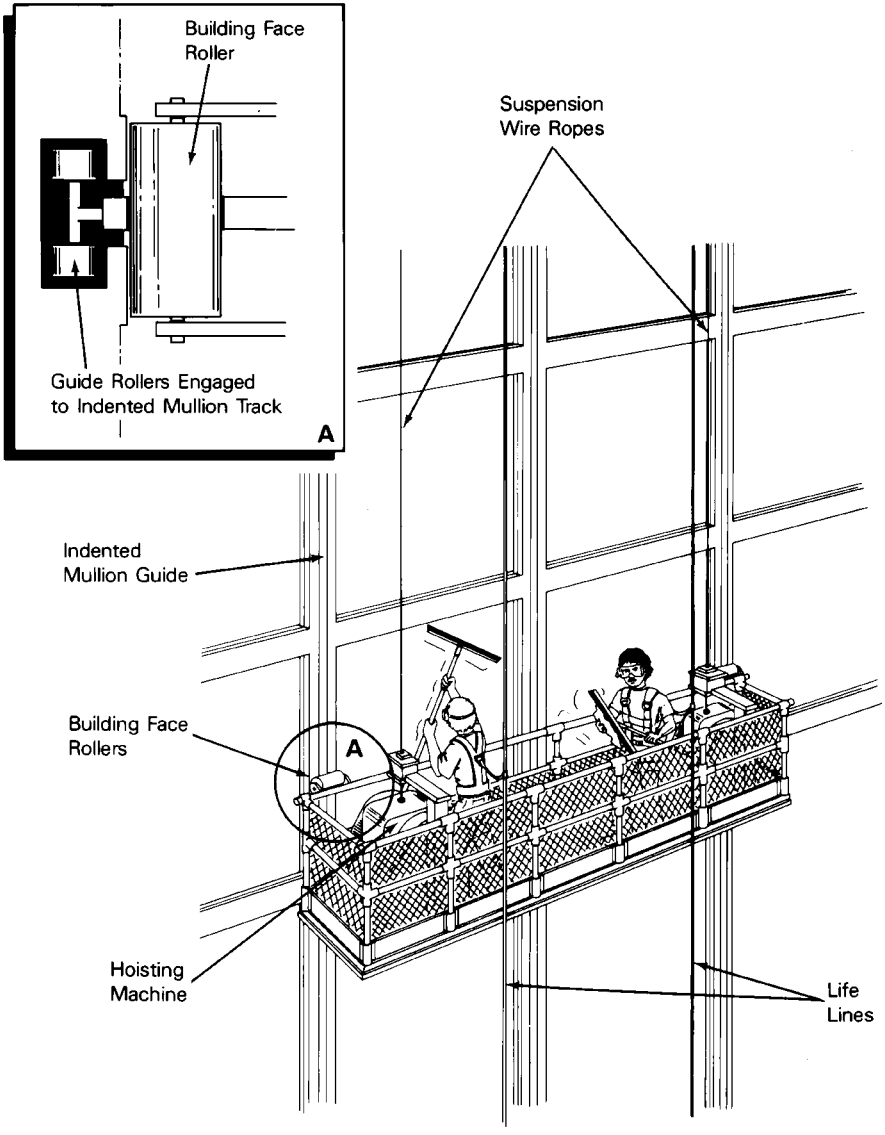Figure 1. Typical Self-Powered Platform--Continuous External or Indented Mullion Guide System