Table A3A - Functions And Subjective Tests QPS REQUIREMENTS					
Entry Number	Operations Tasks	Simulator Level			
		A	B	C	D
	landing.				
7.a.1.b	Autopilot/autothrottle coupled approach and manual landing.	X	X	X	X
7.a.1.c	Autopilot/autothrottle coupled approach, engine(s) inoperative.	X	X	X	X
7.a.1.d	Manual approach, engine(s) inoperative.	X	X	X	X
7.a.1.e	HUD/EFVS			X	X
7.a.2	CAT II published approaches.				
7.a.2.a	Autopilot/autothrottle coupled approach to DH and landing (manual and autoland).	X	X	X	X
7.a.2.b	Autopilot/autothrottle coupled approach with one-engine-inoperative approach to DH and go-around (manual and autopilot).	X	X	X	X
7.a.2.c	HUD/EFVS			X	X
7.a.3	CAT III published approaches.				
7.a.3.a	Autopilot/autothrottle coupled approach to landing and roll-out (if applicable) guidance (manual and autoland).	X	X	X	X
7.a.3.b	Autopilot/autothrottle coupled approach to DH and go-around (manual and autopilot).	X	X	X	X
7.a.3.c	Autopilot/autothrottle coupled approach to land and roll-out (if applicable) guidance with one engine inoperative (manual and autoland).	X	X	X	X
7.a.3.d	Autopilot/autothrottle coupled approach to DH and go-around with one engine inoperative (manual and autopilot).	X	X	X	X
7.a.3.e	HUD/EFVS			X	X
7.a.4	Autopilot/autothrottle coupled approach (to a landing or to a go-around):				
7.a.4.a	With generator failure;	X	X	X	X
7.a.4.b.1	With maximum tail wind component certified or authorized;			X	X
7.a.4.b.2	With 10 knot tail wind;	X	X		
7.a.4.c.1	With maximum crosswind component demonstrated or authorized; and			X	X
7.a.4.c.2	With 10 knot crosswind.	X	X		
7.a.5	PAR approach, all engine(s) operating and with one or more engine(s) inoperative	X	X	X	X
7.a.6	MLS, GBAS, all engine(s) operating and with one or more engine(s) inoperative	X	X	X	X
7.b.	**Non-precision approach.**				
7.b.1	Surveillance radar approach, all engine(s) operating and with one or more engine(s) inoperative	X	X	X	X
7.b.2	NDB approach, all engine(s) operating and with one or more engine(s) inoperative	X	X	X	X